

Fixed-parameter tractable constraint satisfaction

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Talk Outline

- Refined view at hierarchies of tractable CSP (like bounded treewidth)
- Trade-off: Generality vs Performance
- Framework of Parameterized Complexity
- Continue line of research [GOTTLOB, SCARCELLO, SIDERI 02]
- New hardness results, new tractability results
- Via “domination” complete classification for a large number of combinations of parameters
- Hardness results apply to general width parameters (like hypertree width) and to Boolean CSP

Tractable CSPs

- Tractable classes of CSP instances
- Hierarchies of tractable classes:

$$\mathcal{C}_1 \subset \mathcal{C}_2 \subset \dots \subset \mathcal{C}_k \subset \dots$$

- Hierarchies based on “width parameters” like *treewidth* or *hypertree width*

$$\mathcal{C}_k = \{ I : \text{width}(I) \leq k \}$$

i.e., restrictions on the left hand side.

Generality vs Performance

$$\mathcal{C}_1 \subset \mathcal{C}_2 \subset \dots \subset \mathcal{C}_k \subset \dots$$

$$O(n) \quad O(n^2) \quad \dots \quad O(n^k) \quad \dots$$

$$O(c_1 n^\alpha) \quad O(c_2 n^\alpha) \quad \dots \quad O(c_k n^\alpha) \quad \dots$$

Cost of more generality:

- **non-uniform polynomial time:** pay with polynomial of higher order.
- **uniform polynomial time:** we pay only by a larger constant factor.

Research Question

Which hierarchies/parameterizations allow uniform polytime solution and which don't?

... and what theoretical framework is suitable for this investigation?

Parameterized Complexity

- “Two dimensional complexity theory”
- Initiated by Downey and Fellows in late 1980s
- Now significant branch in algorithm design with 100s of research papers (two new monographs [FLUM & GROHE 06], [NIEDERMEIER 06])

fixed-parameter tractable
(FPT)

solvable in uniform polytime
rich toolkit for developing
FPT algorithms

W[1]-hard

very unlikely to be uniform
polytime
evidence via completeness
theory.

- Distinction has been shown robust and well related to practicability.

Parameterized CSP

- *CSP parameter*: a computable function $p : \mathbf{CSP} \rightarrow \{1, 2, \dots\}$.
- parameterized problem: $\mathbf{CSP}(p)$
 - Instance: CSP instance I , integer k with $p(I) \leq k$.
 - Parameter: k .
 - Question: is I satisfiable?
- “promise problem”
- Also combination of parameters, $\mathbf{CSP}(p_1, \dots, p_r)$.

Basic CSP parameters

- **vars**: number of variables
- **dom**: size of domain
- **arity**: max arity of constraints
- **ovl**: max overlap of constraint scopes
- Observations:
 - **CSP(dom)** is not FPT.
(3-colorability)
 - **CSP(vars)** is $W[1]$ -hard
[PAPADIMITRIOU & YANNAKAKIS 99]
 - **CSP(dom, vars)** is FPT
(check $\mathbf{dom}^{\mathbf{vars}}$ assignments)

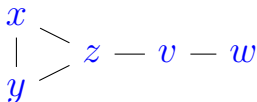
W[1]-hardness of **CSP(vars)** [P&Y 99]

- Parameterized reduction from *k-CLIQUE*:
- Given a graph $G = (V, E)$
- Construct CSP instance:
 - k variables x_1, \dots, x_k .
 - domains: $D(x_i) = V$.
 - $\binom{k}{2}$ binary constraints $((x_i, x_j), E)$.

treewidth parameters

- $\mathbf{tw}(I)$ treewidth of *primal graph*

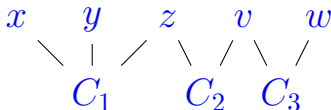
Example: C_1 on x, y, z ; C_2 on z, v ; C_3 on v, w .



- $\mathbf{tw}^d(I)$ treewidth of *dual graph*



- $\mathbf{tw}^*(I)$ treewidth of *incidence graph* (most general)



Classification Theorem

Our new results allow to classify all combinations of the aforementioned parameters,

$$S \subseteq \{\mathbf{tw}, \mathbf{tw}^d, \mathbf{tw}^*, \mathbf{dom}, \mathbf{arity}, \mathbf{ovl}\}$$

whether **CSP**(S) is FPT (uniformly polytime) or not.

... $2^6 = 64$ subsets to consider ...

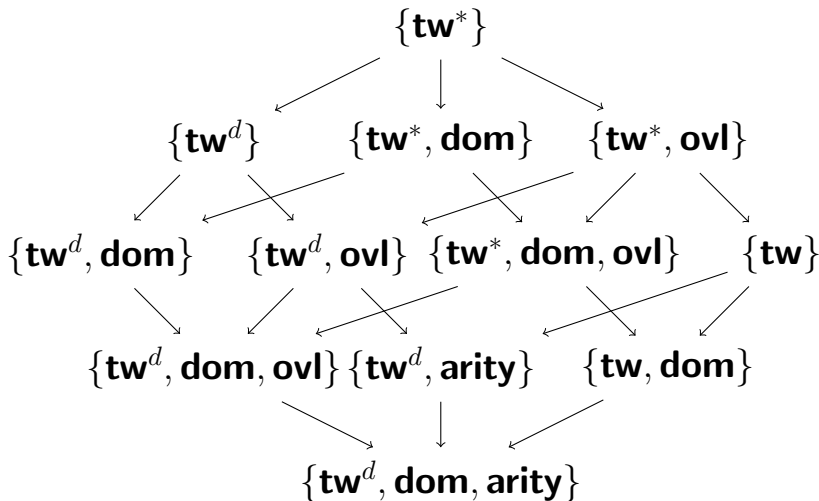
Domination

- If **arity** is bounded, **ovl** gets automatically bounded.
- So **ovl** is the more general parameter. We say that **ovl dominates arity**.
- First consequence: not all combinations are interesting:
E.g.: **CSP**(..., **ovl**, **arity**) is already covered by **CSP**(..., **arity**).
- Second consequence: If X dominates Y then
 - **CSP**(X) is FPT \Rightarrow **CSP**(Y) is FPT
 - **CSP**(Y) is not FPT \Rightarrow **CSP**(X) is not FPT.

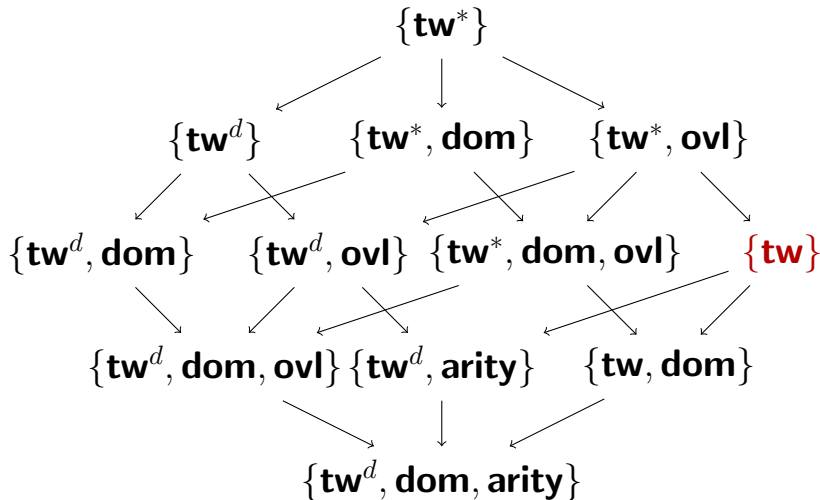
Domination of width parameters

- **tw*** dominates **tw**
[KOLAITIS & VARDI 00].
- **tw*** dominates **tw^d**
(by symmetric argument).
- **arity** dominates **tw**
(large arity gives large cliques).
- **tw** dominates **vars**
(trivial).
- 12 non-redundant subsets remain to consider,
partially ordered by dominance:

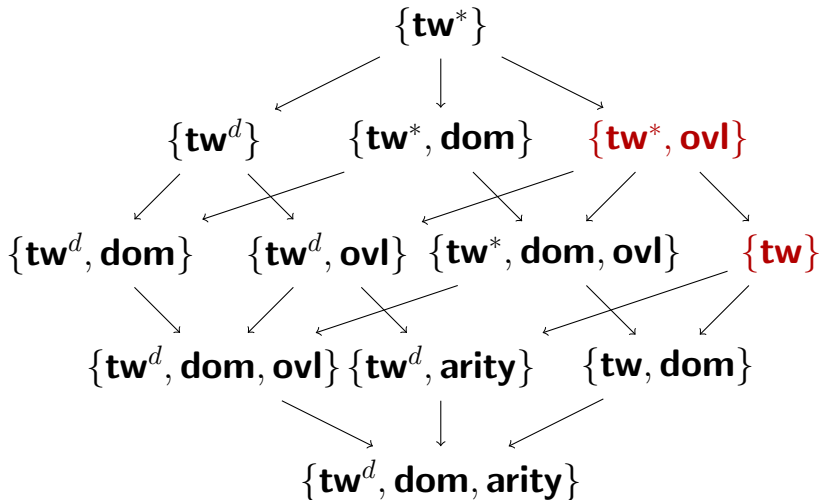
The Domination Lattice



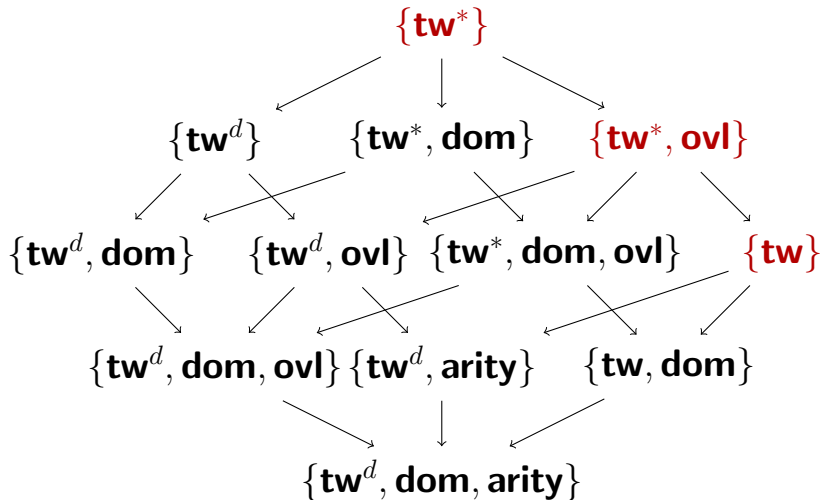
W[1]-hardness via [P&Y 99]



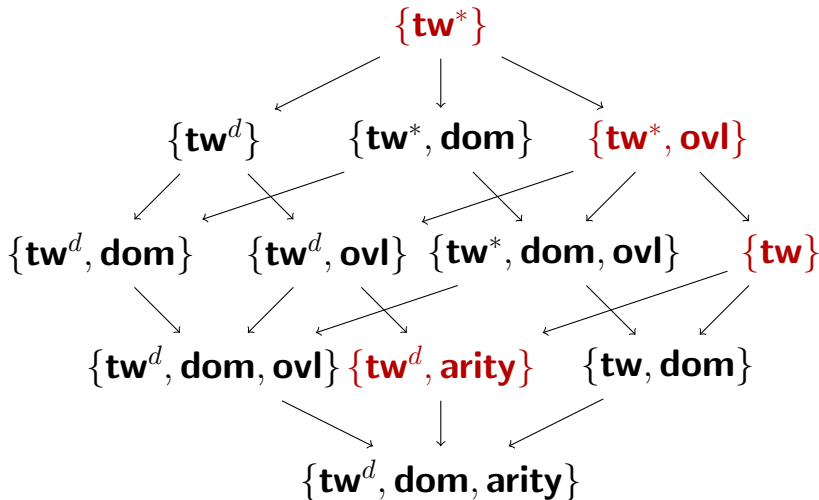
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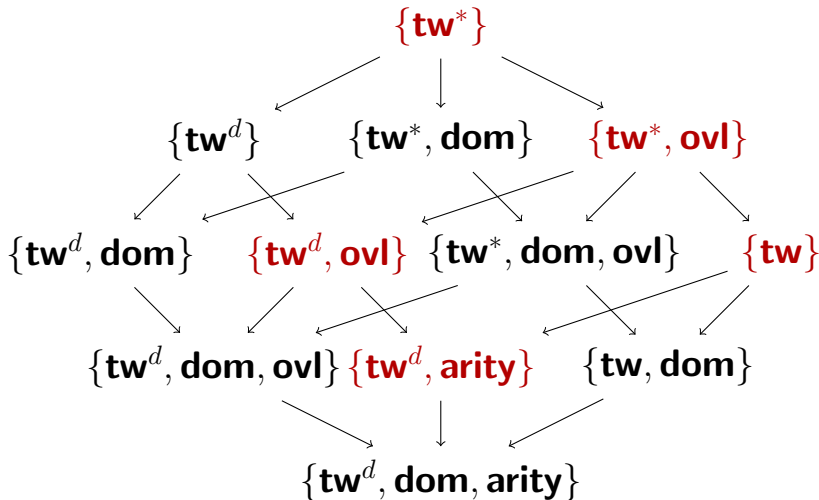
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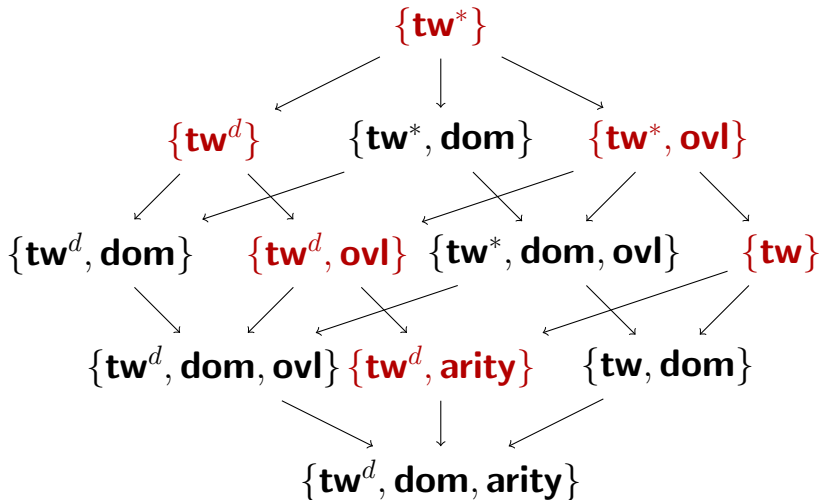
Same reduction works!



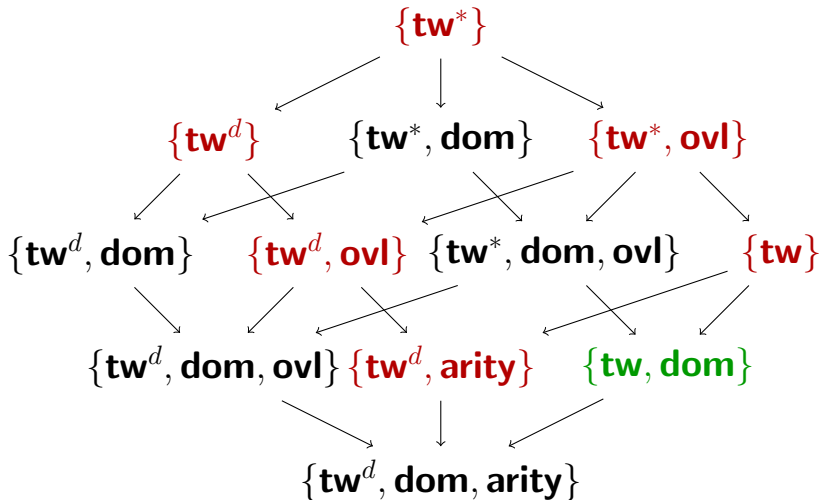
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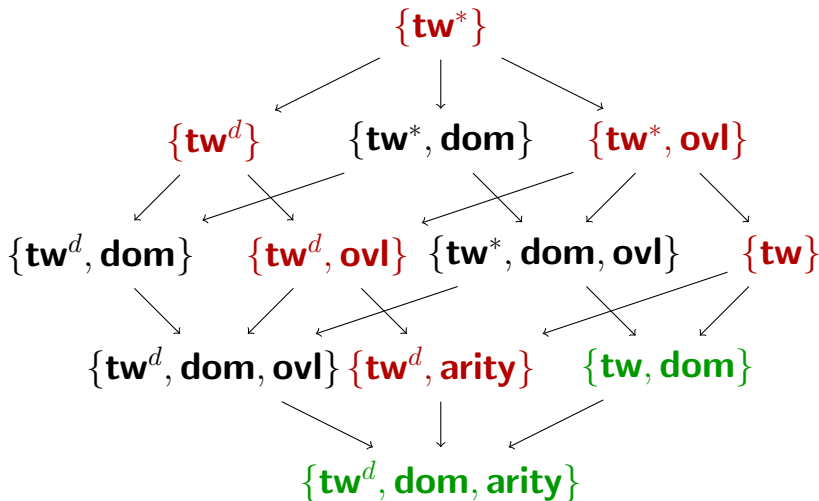
Same reduction works!



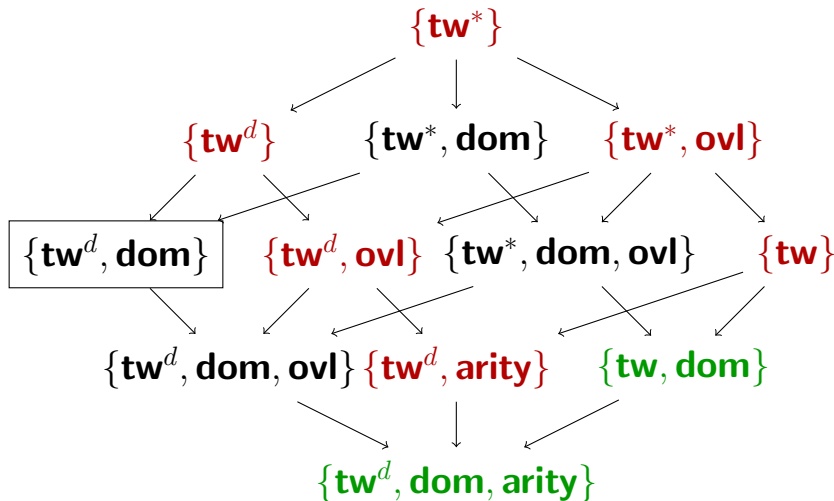
FPT by [GOTTLOB, SCARCELLO, SIDERI 02]



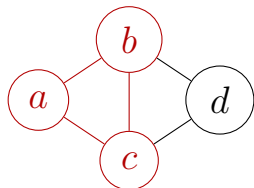
FPT by [GOTTLOB, SCARCELLO, SIDERI 02]



Complexity of $\text{CSP}(\text{tw}^d, \text{dom})$



Reduction from k -CLIQUE



Solution

$a_1 = 1, b_2 = 1, c_3 = 1,$
(all other variables = 0)

corresponds to 3-clique

$a, b, c.$

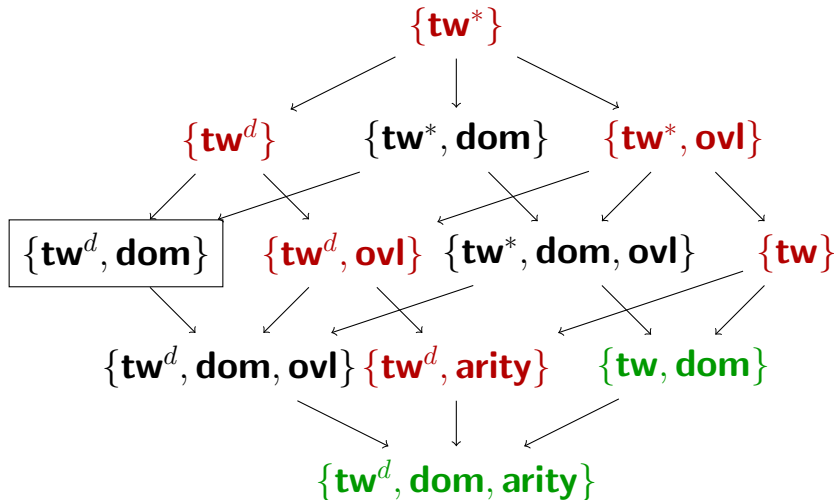
treewidth of dual graph is
bounded

| a_1 | b_1 | c_1 | d_1 | a_2 | b_2 | c_2 | d_2 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |

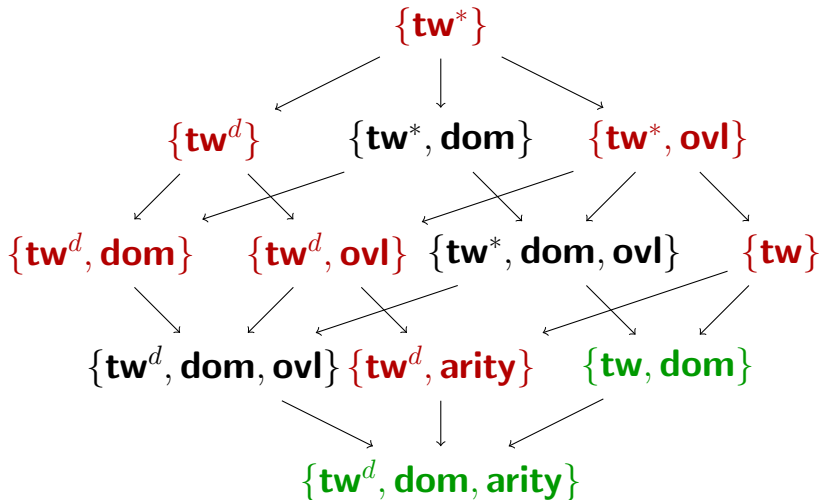
| a_1 | b_1 | c_1 | d_1 | a_3 | b_3 | c_3 | d_3 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |

| a_2 | b_2 | c_2 | d_2 | a_3 | b_3 | c_3 | d_3 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |

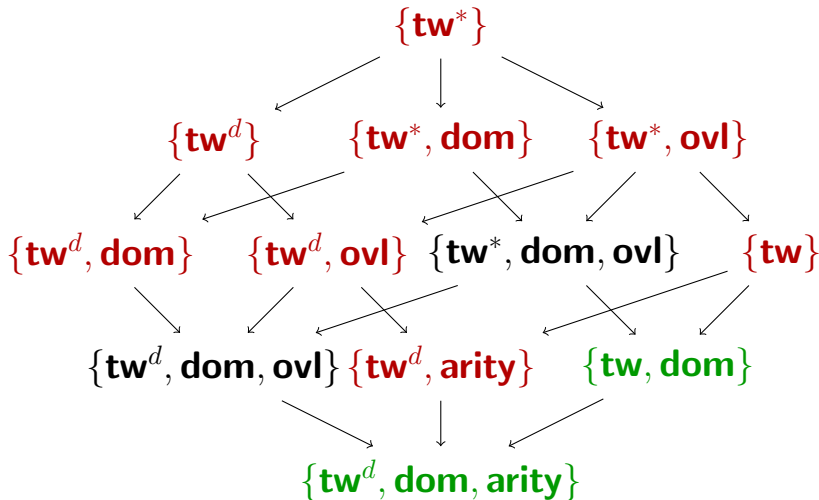
Updated Lattice



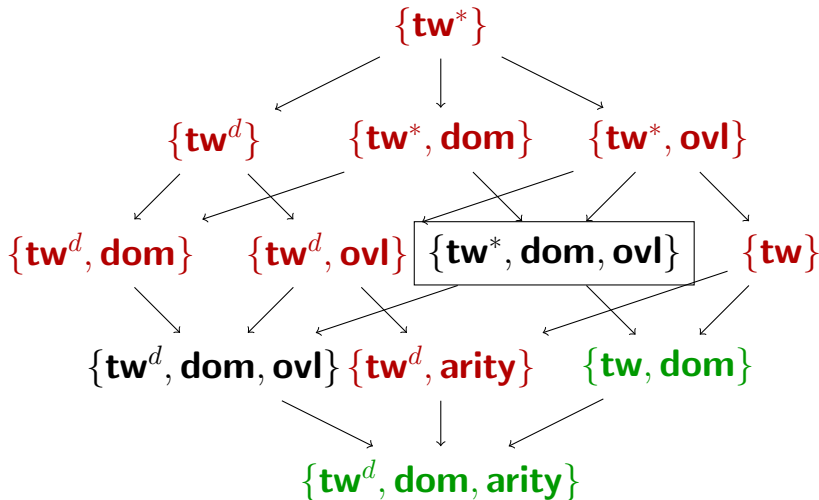
Updated Lattice



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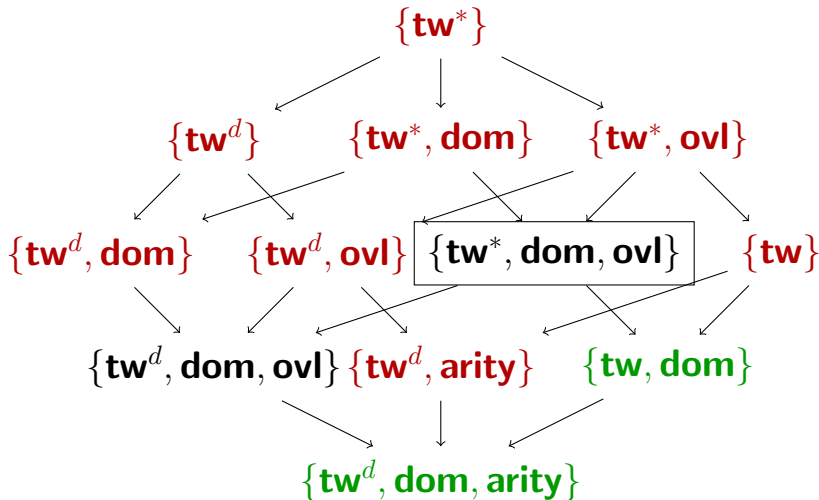
Complexity of $\text{CSP}(\text{tw}^*, \text{dom}, \text{ovl})$?



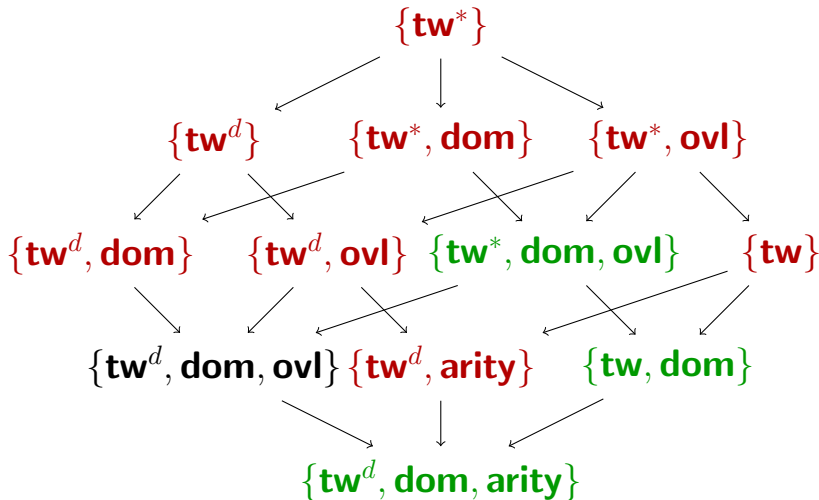
New FPT result

- *Theorem:* $\text{CSP}(\text{tw}^*, \text{dom}, \text{ovl})$ is FPT.
- via *dynamic programming* algorithm on “nice” tree-decompositions
partial solutions are collected and in a bottom-up traversal of tree-decomposition.
- Technically complicated since we need to deal with “partial constraints.”

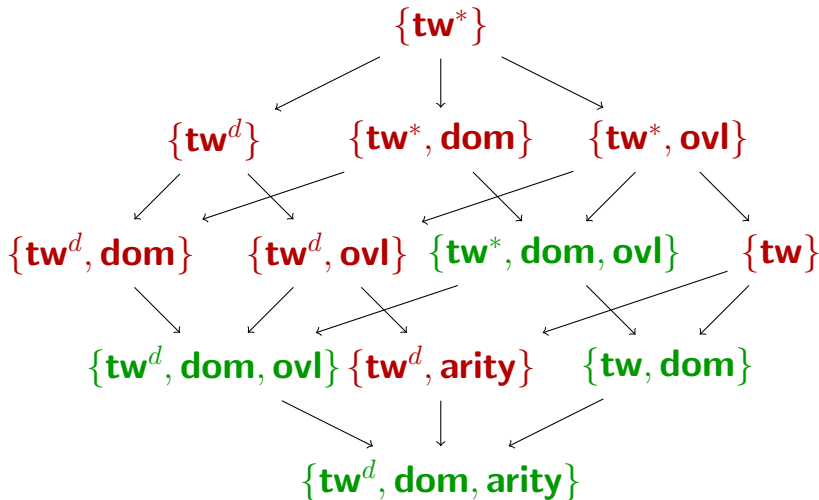
Updated lattice



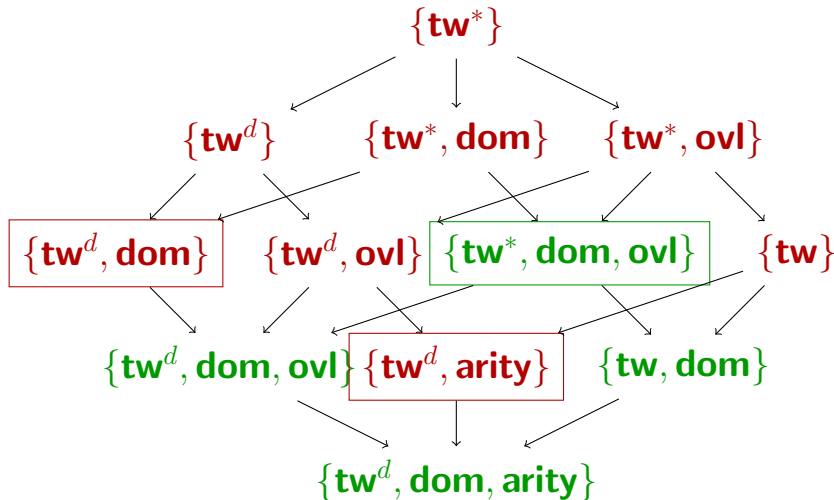
Updated lattice



Updated lattice



Border cases



Stronger parameterizations

- More general parameters have been suggested (defined in terms of constraint hypergraphs), such as:
 - *(generalized) hypertree width*
[GOTTLOB, LEONE, SCARCELLO 01]
 - *spread-cut width*
[COHEN, JEAUVONS, GYSSENS 05]
 - *fractional hypertree width*
[GROHE & MARX 06]
- It was open whether **CSP**(p , **dom**) is fixed-parameter tractable for the above parameters p .

Further hardness results

- All the above parameters p dominate \mathbf{tw}^* .
- Hence: **CSP**(p, \mathbf{dom}) is $W[1]$ -hard.
- Note 1:
 - Recognizing instances of bounded hypertree-width is $W[2]$ -hard [GOTTLOB, GROHE, MUSLIU, SAMER, SCARCELLO, WG'05]
 - However, there is a (non-uniform) polytime algorithm for CSP of bounded hypertree width that *avoids the recognition process* [DALMAU & CHEN CP05].
- Note 2: hardness results hold for **CSP**_{boole}(p).

Boolean CSP vs SAT

- New hardness actually holds for Boolean CSP.
- i.e., $\mathbf{CSP}_{\text{bool}}(\mathbf{tw}^*)$ is $W[1]$ -hard.
- In contrast to $\mathbf{SAT}(\mathbf{tw}^*)$ which is FPT.

Summary

- More refined view on hierarchies of tractable CSP
- *Generality vs performance* in terms of parameterized complexity
- New hardness results for general width parameters.
- New fixed-parameter algorithm for **CSP(dom, owl, tw*)** that captures all previously known FPT cases
- Domination as tool to ease classification
- Classified all combinations of basic and treewidth parameters.

Further research

- Study parameterized complexity of further parameters.
- Parameters defined via *backdoor sets* (results for SAT).
- Any interesting parameters based on constraint languages?