

Constraint Satisfaction with Succinctly Specified Relations

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CSP instances

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Restrictions on $\mathcal{B}(\mathcal{I})$ are called **constraint language restrictions**.

For classes \mathbf{K}, \mathbf{L} of relational structures:

CSP(\mathbf{K}, \mathbf{L})

Instance: CSP instance \mathcal{I}
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- ▶ We are mainly interested in restrictions of the form $\text{CSP}(\mathbf{K}, -)$ (**structural restrictions**).

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Two important ideas

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Theorem (Dalmau, Kolaitis, and Vardi 2002)

Let \mathbf{K} be a class of structures of bounded tree width modulo homomorphic equivalence.

Then $\text{CSP}(\mathbf{K}, -)$ is tractable.

Bounded arity

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Assume that $\text{FPT} \neq \text{W}[1]$ (or stronger: $3\text{-SAT} \notin \text{DTIME}(2^{o(n)})$). For every recursively enumerable class \mathbf{K} of structures of bounded arity, the following are equivalent:

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There are classes \mathbf{K} of graphs of unbounded treewidth modulo homomorphic equivalence such that $\text{CSP}(\mathbf{K}, -) \in \text{NP}[\log^2 n]$.

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- ▶ The requirement that \mathbf{K} be recursively enumerable is inessential. With a slightly stronger complexity theoretic assumption, we can get rid of it.

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A new version of the paper is on my webpage:

<http://www.informatik.hu-berlin.de/~grohe/pub/gro06b+.html>

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Let k be a constant and $\mathcal{I} = (V, D, C)$ a CSP-instance. Suppose that the constraints

$$R_1 x_{11} \dots x_{1r_1}, \dots, R_k x_{k1} \dots x_{kr_k}$$

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Then for the set S of all solutions of \mathcal{I} , we have:

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($S \subseteq R_1 \times \dots \times R_k$ if the variable sets are disjoint). Hence

$$|S| \leq |R_1| \cdot |R_2| \cdot \dots \cdot |R_k| \leq |\mathcal{I}|^k,$$

and S can be computed in polynomial time.

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That's all great — but wait . . .

... haven't we just proved
($N = 1 \vee P = 0$)

- ▶ If viewed as a (Boolean) CSP, the satisfiability problem $\text{SAT}(\Phi)$ for the following class of formulas is tractable:

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- ▶ Hence $P = NP$.

Conclusion

- ▶ By a simple reduction to constraint satisfaction problems, we have proved the satisfiability problem to be in polynomial time and hence $P = NP$.
- ▶ This impressively shows the power of the algorithmic ideas developed in the area.

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In this work, we try to initiate a systematic study of the complexity of CSP with implicitly represented relations.

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DNF Representations

DNF-formulas form natural large class of formulas with a tractable satisfiability problem.

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DNF-formulas form natural large class of formulas with a tractable satisfiability problem.

Therefore, we decided to choose **DNF-formulas** as **succinct representations** of Boolean constraint relations.

Arbitrary domains — the GDNF-representation

Definition

Let D be a set. A **generalised DNF (GDNF) representation** of a relation $R \subseteq D^k$ is an expression of the form

$$\bigcup_{i=1}^m (P_{i1} \times \cdots \times P_{ik})$$

where $m \geq 0$ and $P_{ij} \subseteq D$ for $1 \leq i \leq m, 1 \leq j \leq k$.

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Remark

The GDNF enables us to represent relations of size $\Omega(D^k)$ by expressions of size $O(m \cdot |D| \cdot k)$.

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For all $n \in \mathbb{N}$: $[n] = \{1, \dots, n\}$.

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Example

Let $MAX \subseteq [n]^{k+1}$ be defined by

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Then $|MAX| = \Omega(n^k)$.

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Then $|\text{MAX}| = \Omega(n^k)$.

MAX has the following GDNF-representation of size $O(k^2 \cdot n^2)$:

$$\bigcup_{\substack{1 \leq i \leq k \\ 1 \leq j \leq n}} ([i] \times \dots \times [i] \times \underbrace{\{j\}}_{i\text{th place}} \times [i] \times \dots \times [i] \times \underbrace{\{j\}}_{(k+1)\text{st place}}).$$

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- ▶ A CSP-instance \mathcal{I} is **represented in GDNF** if all constraint relations are represented in GDNF.
- ▶ By **$\text{CSP}_{\text{GDNF}}(\mathbf{K}, \mathbf{L})$** is the version of the problem $\text{CSP}(\mathbf{K}, \mathbf{L})$ where instances are represented in GDNF.

The incidence structure

Definition

1. **Incidence vocabulary** of a relational vocabulary τ :

$$\tau_I = \{R_1, \dots, R_k \mid R \in \tau \text{ } k\text{-ary}\}$$

(R_i binary).

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$$R_i^{\mathcal{A}_I} = \{((R, a_1, \dots, a_k), a_i) : (a_1, \dots, a_k) \in R^{\mathcal{A}}\}$$

for all k -ary $R \in \tau$ and $i \in [k]$.

Example

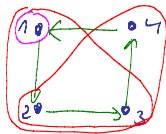
$\{R, E, P\}$ -structure \mathcal{A} :

$$A = \{1, 2, 3, 4\}$$

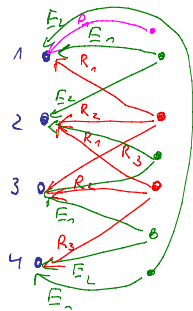
$$R^{\mathcal{A}} = \{(1, 2, 3), (2, 3, 4)\}$$

$$E^{\mathcal{A}} = \{(1, 2), (2, 3), (3, 4), (4, 1)\}$$

$$P^{\mathcal{A}} = \{(1)\}$$



The structure \mathcal{A}_I



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Remark

For all structures \mathcal{A} of arity k :

$$\text{iw}(\mathcal{A}) - 1 \leq \text{tw}(\mathcal{A}) \leq (\text{iw}(\mathcal{A}) + 1) \cdot (k - 1).$$

Theorem

Assume that $\text{FPT} \neq \text{W}[1]$.

For every recursively enumerable class \mathbf{K} of structures of bounded arity, the following are equivalent:

- 1. $\text{CSP}_{\text{GDNF}}(\mathbf{K}, -)$ is tractable.*
- 2. \mathbf{K} has bounded incidence width modulo homomorphic equivalence.*

Constraint language restrictions

Theorem

Let \mathbf{L}_k be the class of all relational structures having a near-unanimity polymorphism of arity k . For each $k \geq 3$, the problem $\text{CSP}_{\text{GDNF}}(-, \mathbf{L}_k)$ is tractable.

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Let \mathbf{L} be the set of all relational structures invariant under a set function. The problem $\text{CSP}_{\text{GDNF}}(-, \mathbf{L})$ is tractable.

Other representations

- ▶ **Ordered binary decision diagrams (OBDDs)** are another representation of Boolean relations with nice algorithmic properties. In particular, the satisfiability problem is decidable.

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- ▶ **Ordered binary decision diagrams (OBDDs)** are another representation of Boolean relations with nice algorithmic properties. In particular, the satisfiability problem is decidable.
- ▶ We considered the natural generalization of OBDDs to arbitrary finite domains and obtained initial results.